

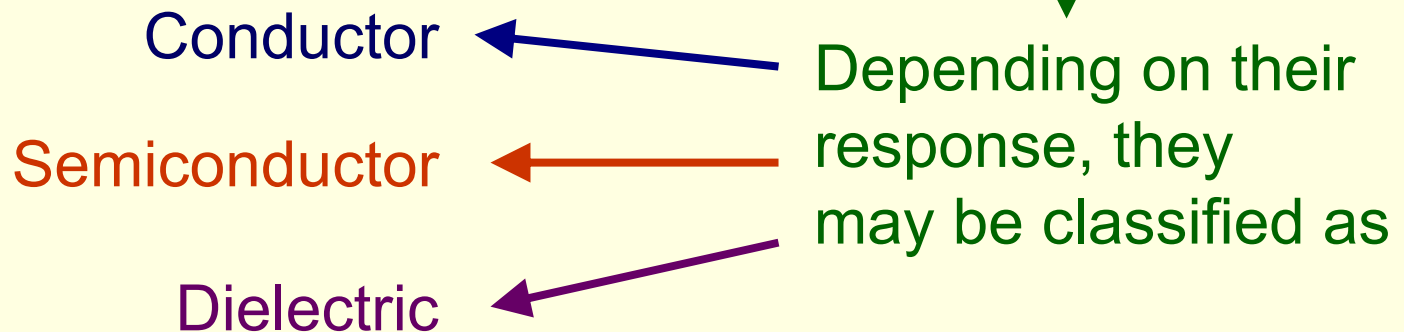


FIELDS AND MATERIALS

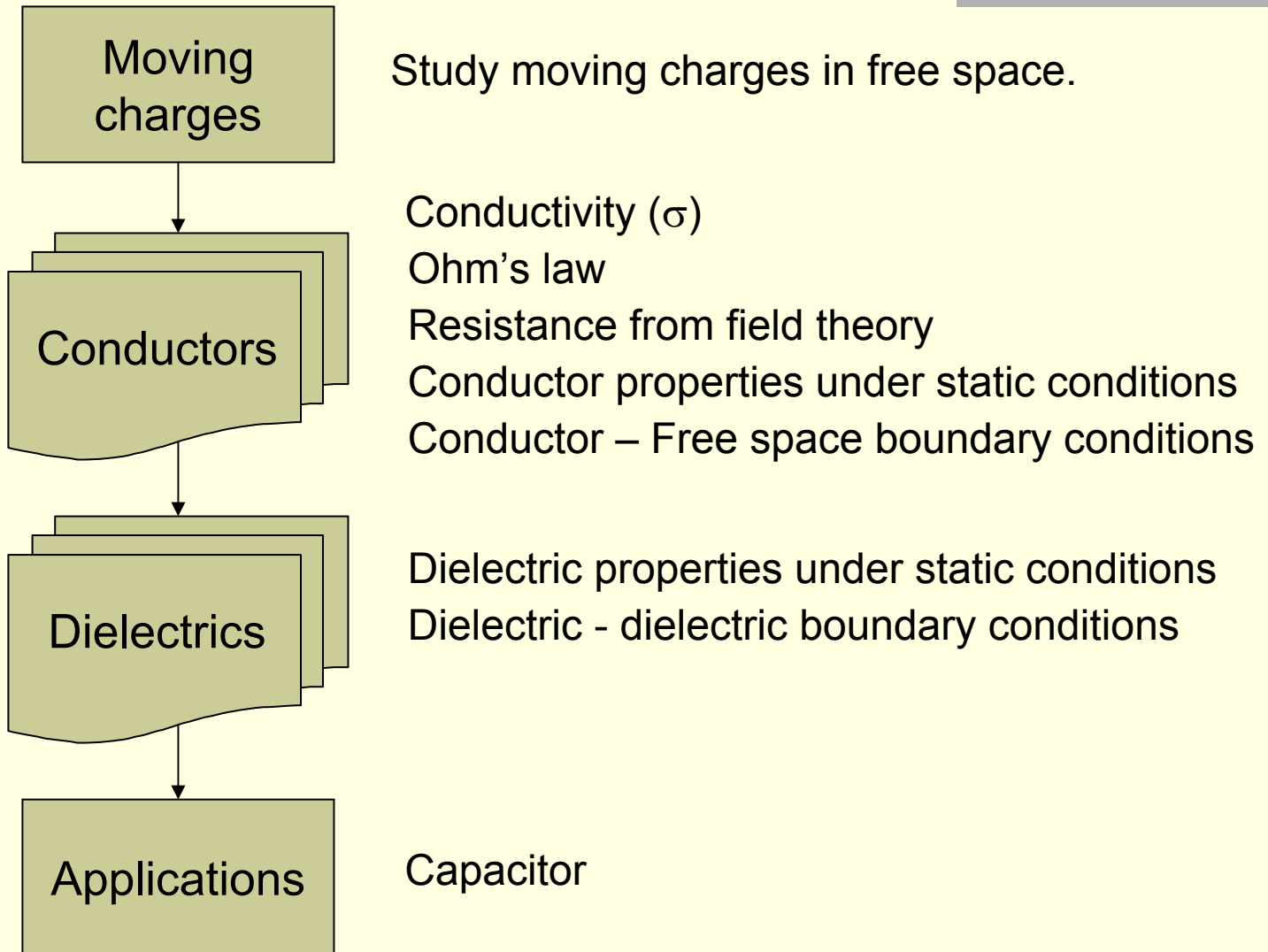
INTRODUCTION

- In our discussion of electric field thus far, we considered the medium to be free space and source to be static charges.
- We shall now introduce materials.

Contain charged particles that respond to applied field



APPROACH



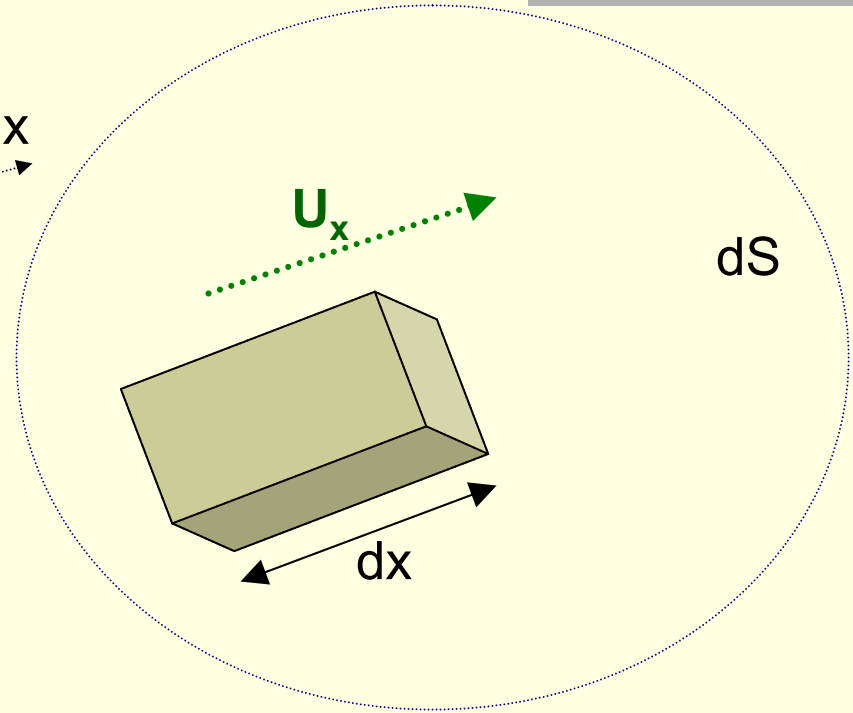
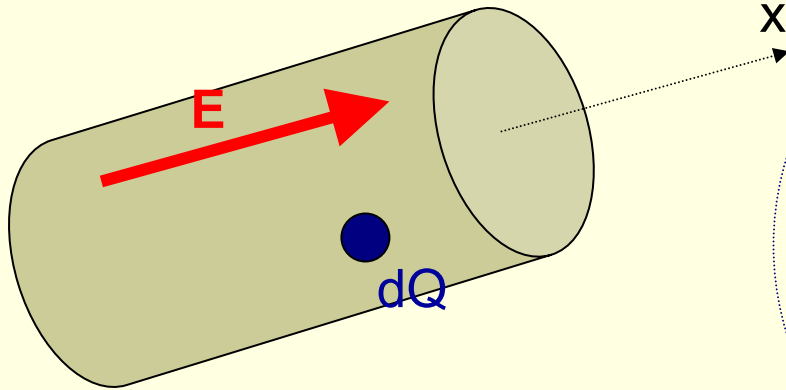
MOVING CHARGES

■ OBJECTIVES

- To introduce concept of current in free space.
- To define convection current and convection current density.
- To explain in your own words the concept of continuity current equation.

DEFINITION

Long cylinder of ρ_v



Current is defined as the movement of charge through a given surface and is equal to the coulombs per second through that surface.

Exploded view of sample dQ

$$dI = \lim_{dt \rightarrow 0} \left[\frac{dQ}{dt} \right]$$

MATHEMATICAL MODEL

$$dI = \lim_{dt \rightarrow 0} \left[\rho_v \frac{dx}{dt} dS \right] = \rho_v U_x dS \quad \longrightarrow \quad \text{Convection current}$$

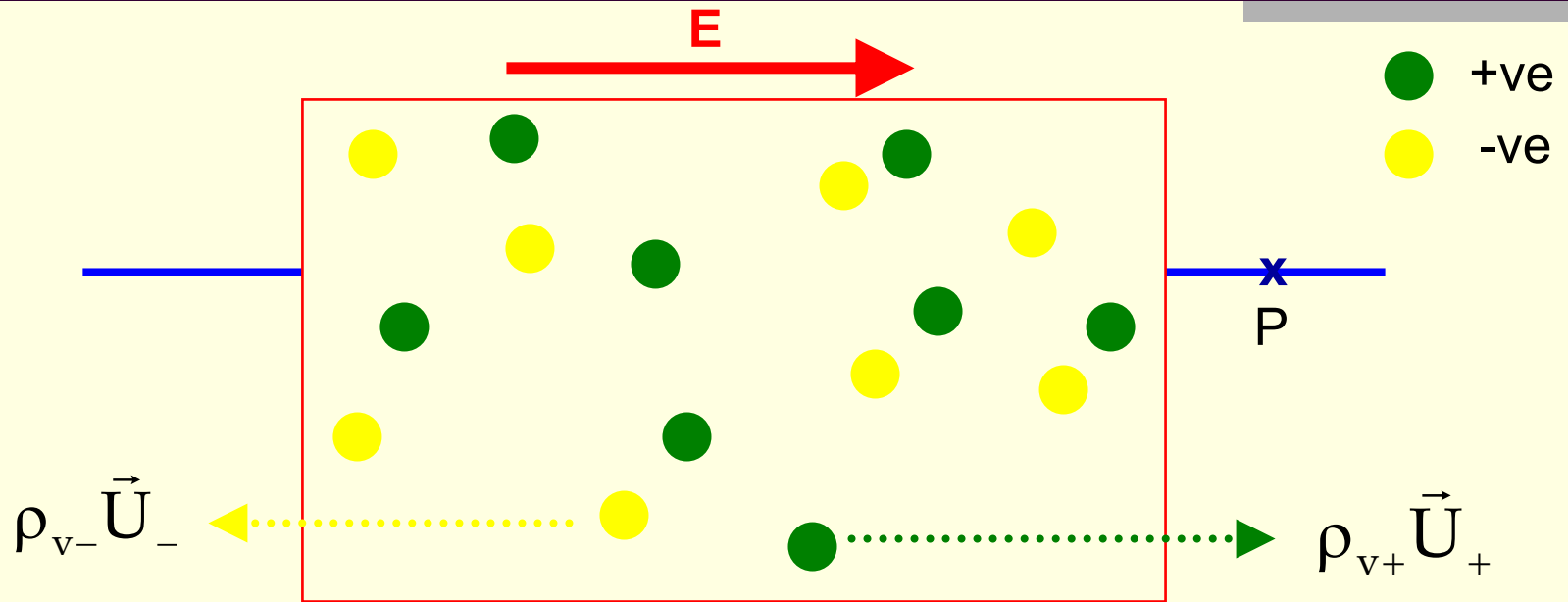
Divide by dS , introducing current density

$$J_x = \lim_{dS \rightarrow 0} \left[\frac{dI}{dS} \right] = \rho_v U_x$$

Written in general vector form

$$\vec{J} = \rho_v \vec{U} \quad \longrightarrow \quad \text{Convection current density}$$

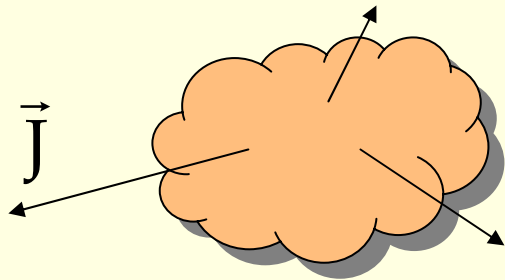
Consider a material where both positive and negative charges exist



At point P, current density $\longrightarrow \vec{J} = \rho_{v+} \vec{U}_+ + \rho_{v-} \vec{U}_-$

Total current $\longrightarrow I = \int_s \vec{J} \cdot d\vec{S}$

CONTINUITY OF CURRENT EQUATION



$$I = \oint_S \vec{J} \cdot d\vec{S} = -\frac{\partial Q_{\text{en}}}{\partial t}$$

Divergence theorem

$$Q_{\text{en}} = \int_V \rho_v dv$$

$$\int_V \nabla \cdot \vec{J} dv$$

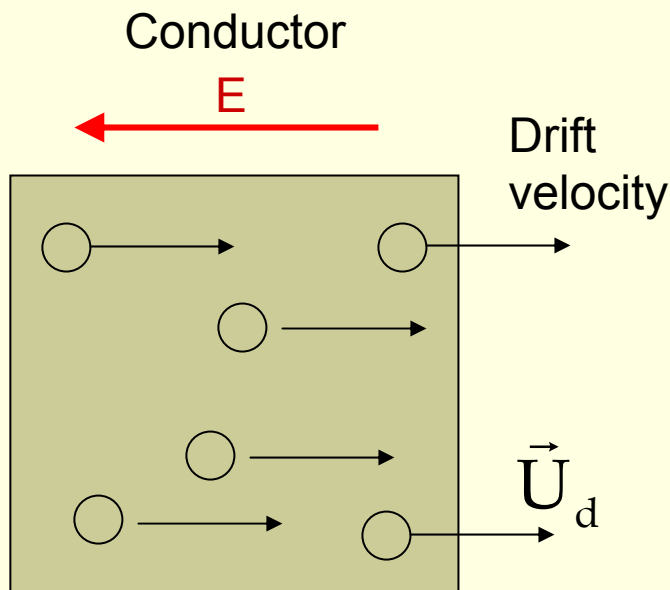
$$-\int_V \frac{\partial \rho_v}{\partial t} dv$$

The point form of the continuity of the current equation

$$\nabla \cdot \vec{J} = -\frac{\partial \rho_v}{\partial t} \quad (\text{A m}^{-3})$$

■ CONDUCTORS AND CONDUCTIVITY

CONDUCTIVITY



○ Electron

Point form
of Ohm's law

$$\vec{U}_d = -\mu_e \vec{E}$$

Electron mobility

$$\vec{J} = -\rho_{ve} \mu_e \vec{E}$$

Conductivity

$$\vec{J} = \sigma \vec{E}$$

CONDUCTIVITY OF SEVERAL MATERIALS

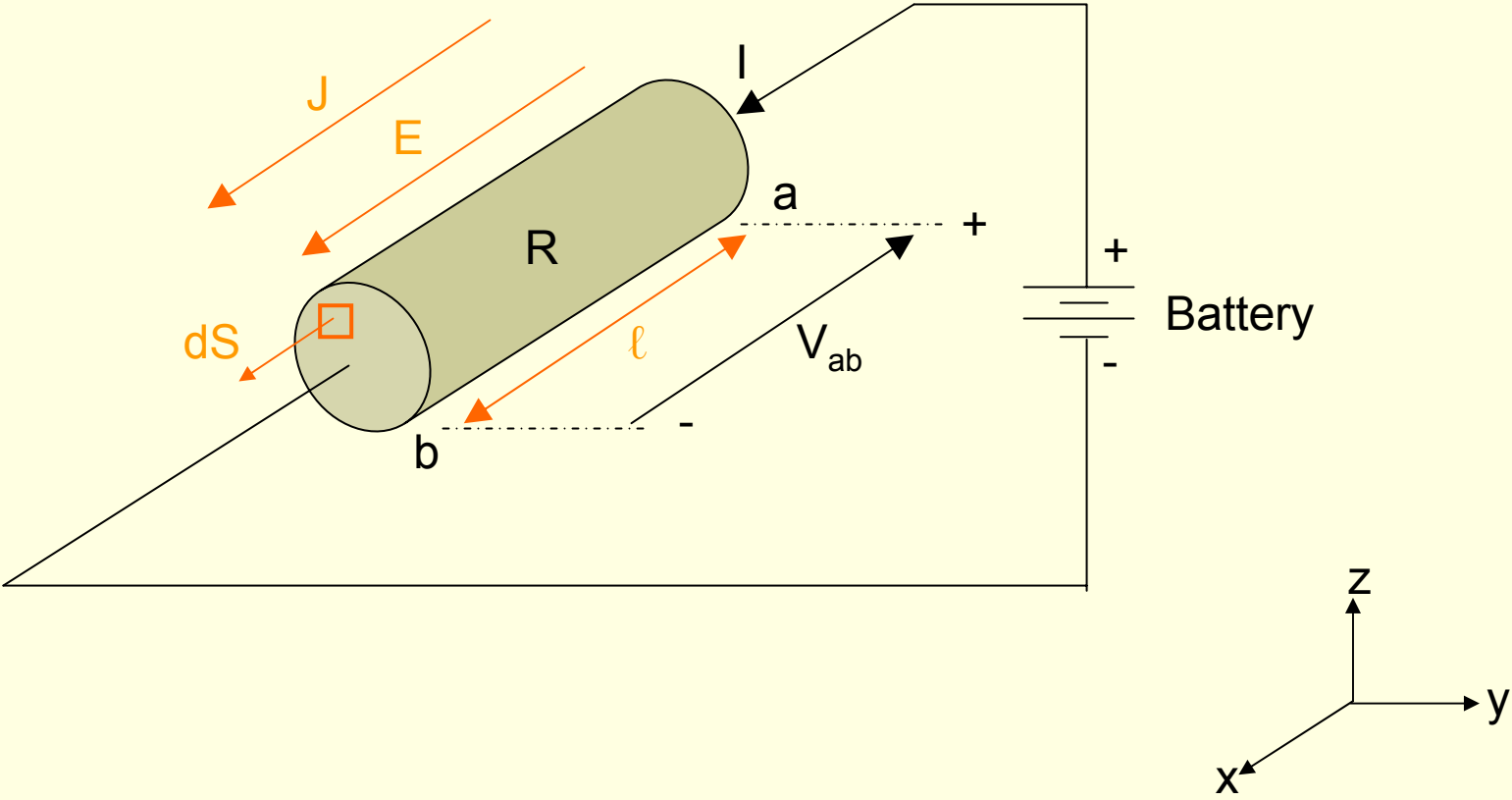
Material	σ (S m ⁻¹)
Silver	6.17×10^7
Iron	1.03×10^7
Ferrite	1.0×10^{-2}
Intrinsic silicon	0.44×10^{-3}
Distilled water	1.0×10^{-4}
Mica	1.0×10^{-15}

↑
↓
Conductors

↑
↓
Intrinsic semiconductors

↑
↓
Insulators

RESISTANCE FROM FIELD THEORY



MATHEMATICAL EQUATION

$$R = \frac{V_{ab}}{I} = \frac{-\int_b^a (\vec{E} \cdot d\vec{\ell})}{\int_s \sigma \vec{E} \cdot d\vec{S}} = \frac{\int_b^a \left(-\frac{\vec{J}}{\sigma} \cdot d\vec{\ell} \right)}{\int_s \vec{J} \cdot d\vec{S}}$$

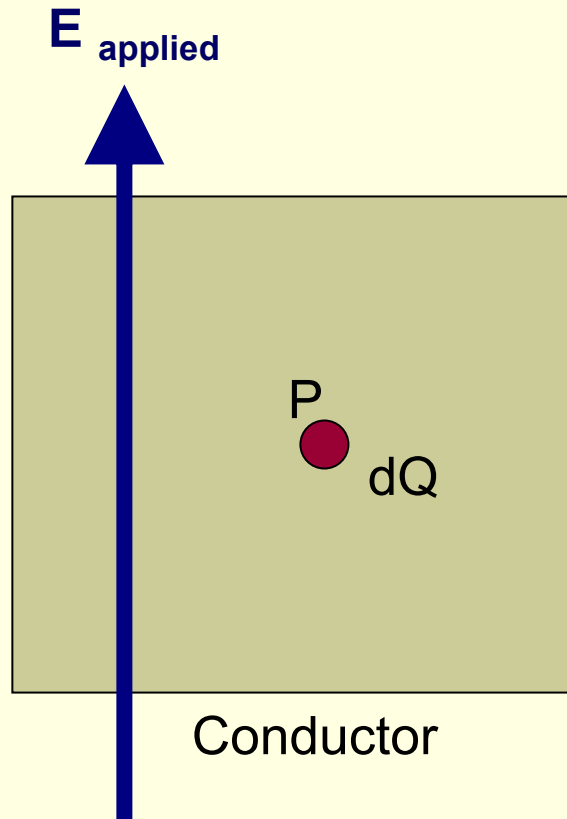
Electrical circuit analysis

From field theory

This concept is useful to conducting material of non-uniform cross section and non-uniform E or J.

■ CONDUCTOR PROPERTIES UNDER STATIC CONDITIONS

MODEL



Point form of the continuity of current equation

$$\nabla \cdot \vec{J} = -\frac{\partial \rho_v}{\partial t} \quad (\text{A m}^{-3})$$

Point form of Ohm's law

$$\vec{J} = \sigma \vec{E}$$

$$\nabla \cdot \vec{E} = -\frac{1}{\sigma} \left(\frac{\partial \rho_v}{\partial t} \right)$$

Point form of Gauss's law

$$\nabla \cdot \vec{E} = \rho_v / \epsilon_0$$

Simple partial differential equation

$$\frac{\partial \rho_v}{\partial t} + \frac{\sigma}{\epsilon_0} \rho_v = 0$$

SOLUTION TO PARTIAL DIFFERENTIAL EQUATION

At point P

$$\rho_V = \rho_V(t) = \rho_{v0} e^{-(\sigma/\epsilon_0)t} = \rho_{v0} e^{-t/t_r}$$

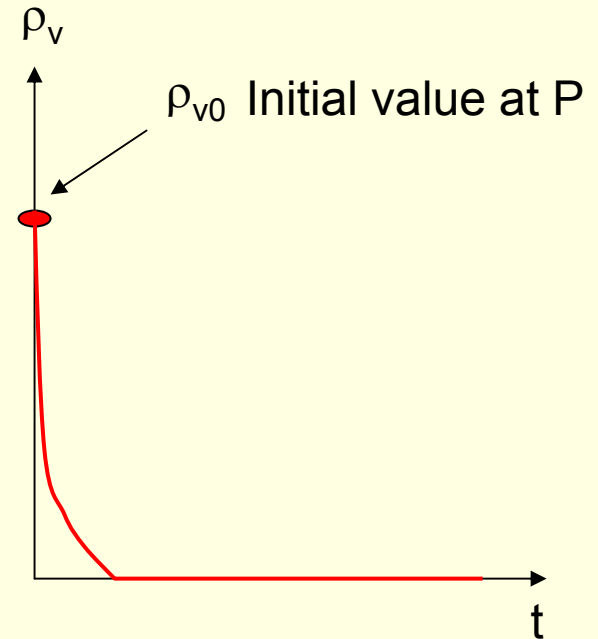
Charge density at $t = 0$

Relaxation time constant

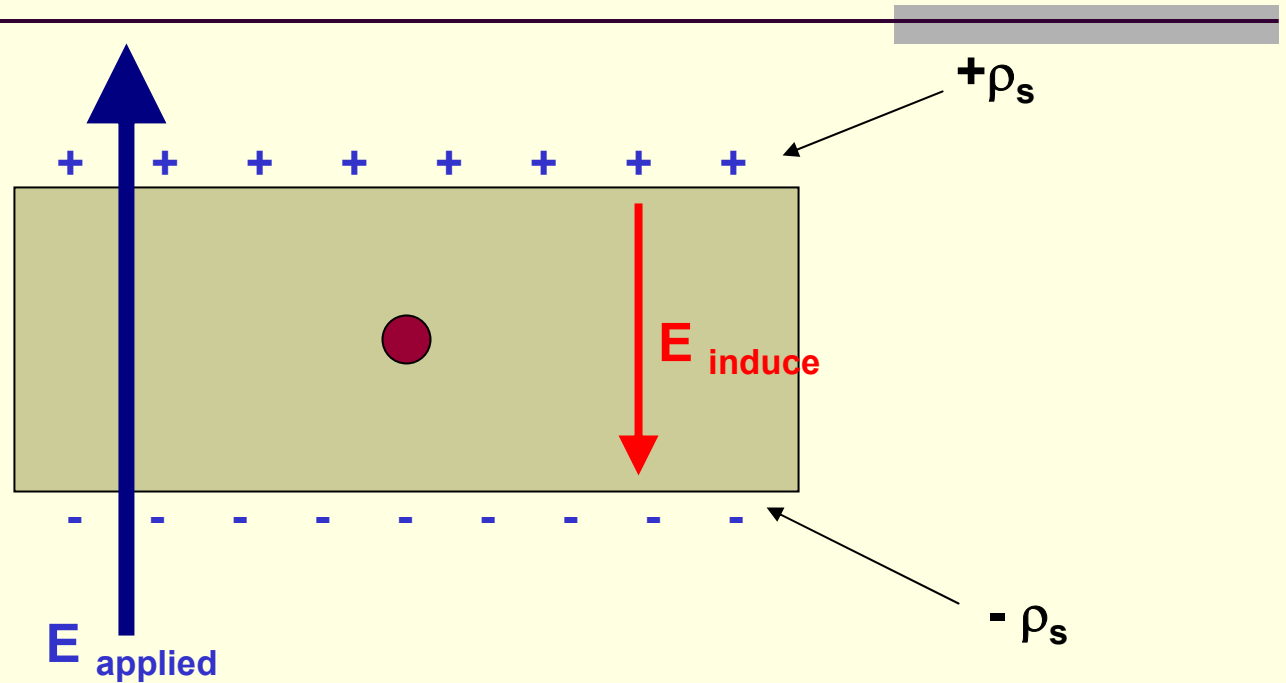
$$t_r = \frac{\epsilon_0}{\sigma}$$

For conductor

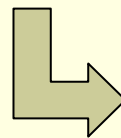
$$\sigma \rightarrow \infty \Rightarrow t_r \rightarrow \text{small}$$



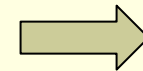
ANALYSIS



$$\mathbf{E}_{\text{net}} = \mathbf{E}_{\text{applied}} - \mathbf{E}_{\text{induce}} \longrightarrow 0$$



$$\nabla V = -\vec{E}$$



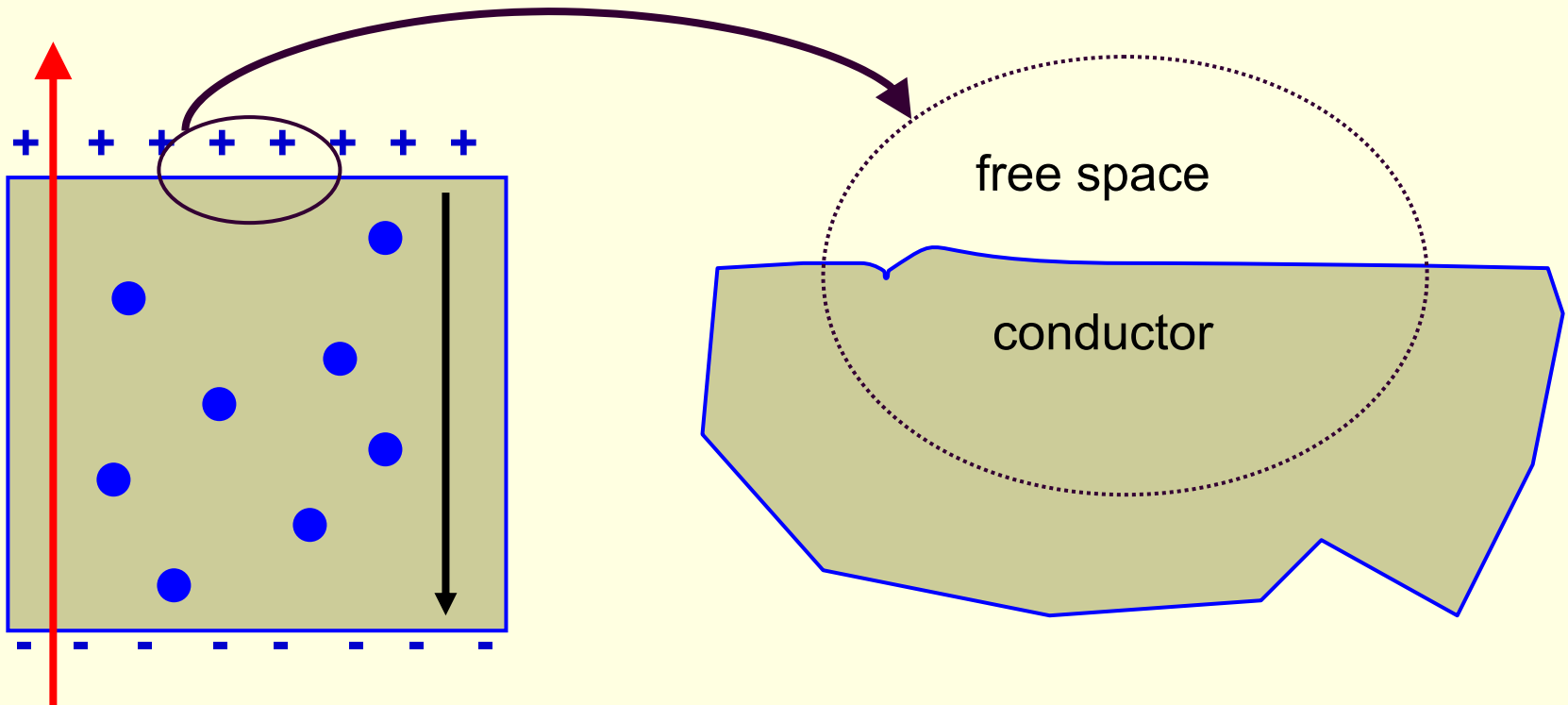
Equipotential
body

CONDUCTOR PROPERTIES UNDER STATIC CONDITION

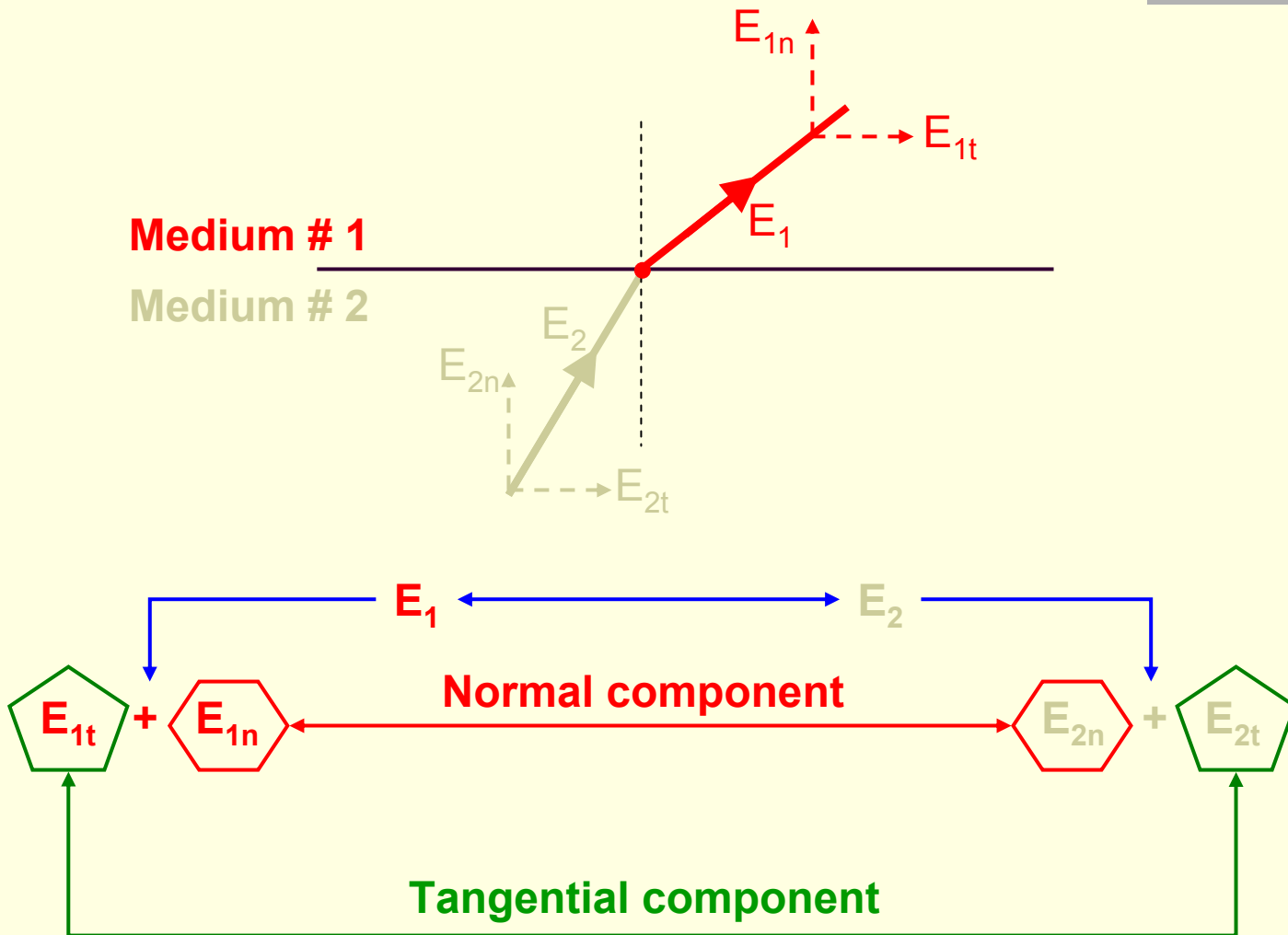
- The net $\rho_v = 0$ inside the conductor.
- The net $\mathbf{E} = 0$ inside the conductor.
- The conductor is an equipotential body.
- Charge density ρ_s , if present, is found only on the surface.

■ CONDUCTOR – FREE SPACE BOUNDARY CONDITIONS

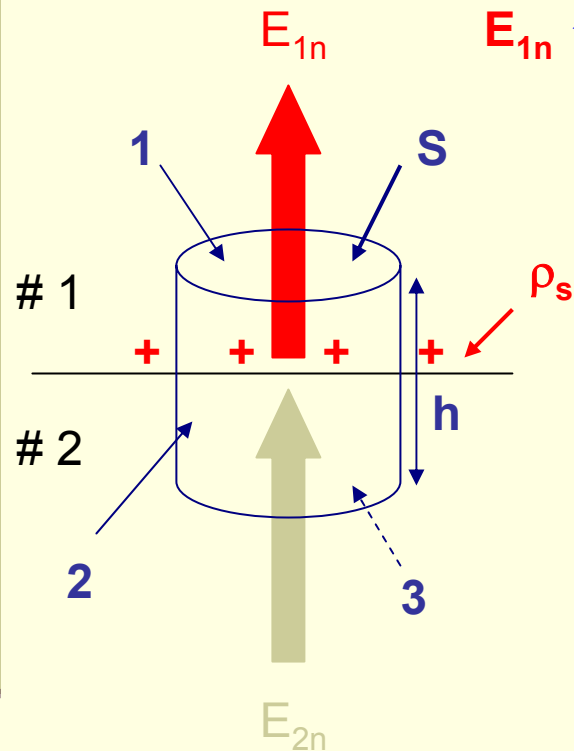
Introduction



GRAPHICAL ILLUSTRATION



NORMAL COMPONENTS



Maxwell's equation (Gauss's law)

$$\oint_S \vec{D} \cdot d\vec{s} = Q_{en}$$

$$\int \vec{D} \cdot d\vec{s}_1 + \int \vec{D} \cdot d\vec{s}_2 + \int \vec{D} \cdot d\vec{s}_3 = \int_S \rho_s ds$$

$D_{1n} \hat{z}$ (pointing to $\int \vec{D} \cdot d\vec{s}_1$)
 0 (pointing to $\int \vec{D} \cdot d\vec{s}_2$)
 $D_{2n} \hat{z}$ (pointing to $\int \vec{D} \cdot d\vec{s}_3$)
 $ds_1 \hat{z}$ (pointing to $d\vec{s}_1$)
 $ds_3 (-\hat{z})$ (pointing to $d\vec{s}_3$)

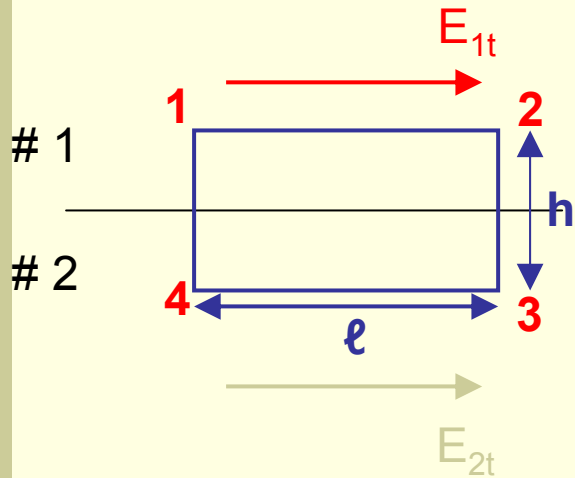
Assume $h \rightarrow 0$

$$D_{1n} S - D_{2n} S = \rho_s S$$

Boundary condition for normal components

$$D_{1n} - D_{2n} = \rho_s$$

TANGENTIAL COMPONENTS



$$\mathbf{E}_{1t} \longleftrightarrow \mathbf{E}_{2t}$$

Maxwell's equation (Conservation of energy)

$$\oint \vec{E} \cdot d\vec{\ell} = 0$$

$$\int_1^2 \vec{E} \cdot d\vec{\ell} + \int_2^3 \vec{E} \cdot d\vec{\ell} + \int_3^4 \vec{E} \cdot d\vec{\ell} + \int_4^1 \vec{E} \cdot d\vec{\ell}$$


Assume again $h \rightarrow 0$


$$E_{1t}l - E_{2t}l = 0$$

Boundary condition for tangential components

$$E_{1t} = E_{2t}$$

CONDUCTOR – FREE SPACE BOUNDARY CONDITION

1  Free space
 ϵ_0

2  Conductor
 ϵ_0

Boundary condition for normal components

$$D_{1n} - \overset{0}{D_{2n}} = \rho_s$$



$$D_{1n} = \rho_s$$

Boundary conditions
for conductor – free
space/dielectric

Boundary condition for tangential components

$$E_{1t} = \overset{0}{E_{2t}}$$

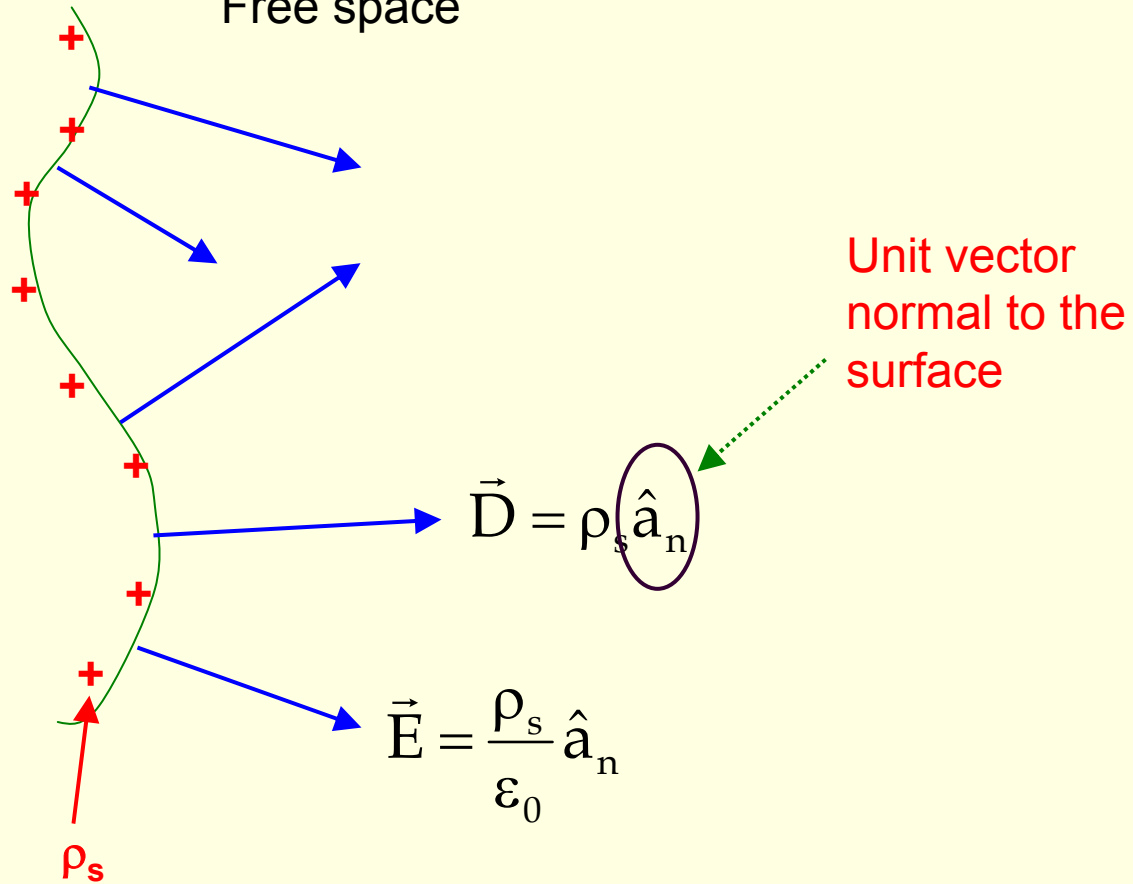


$$E_{1t} = E_{2t} = 0$$

GRAPHICAL ILLUSTRATION

Conductor

Free space

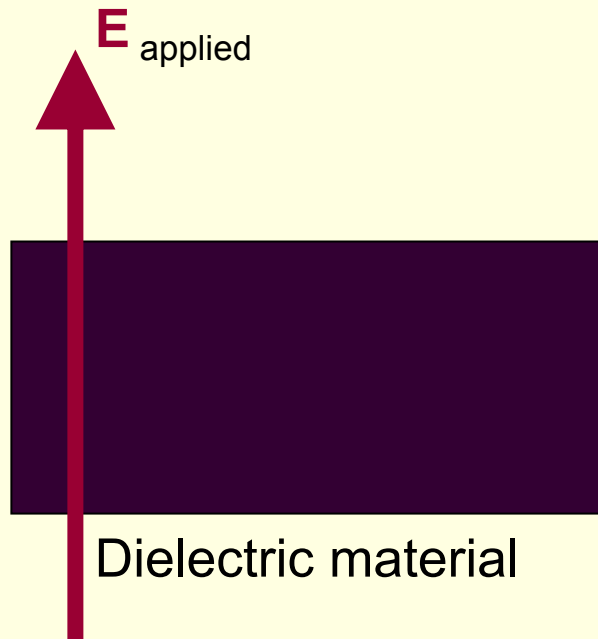


SUMMARIZED THE PRINCIPLES WHICH APPLY TO CONDUCTORS IN ELECTROSTATIC FIELDS

- The static electric field intensity inside a conductor is zero.
- The static electric field at the surface of a conductor is everywhere directed normal to that surface.
- The conductor surface is an equipotential surface.

■ DIELECTRIC MATERIALS

DIELECTRIC MATERIAL UNDER STATIC CONDITIONS



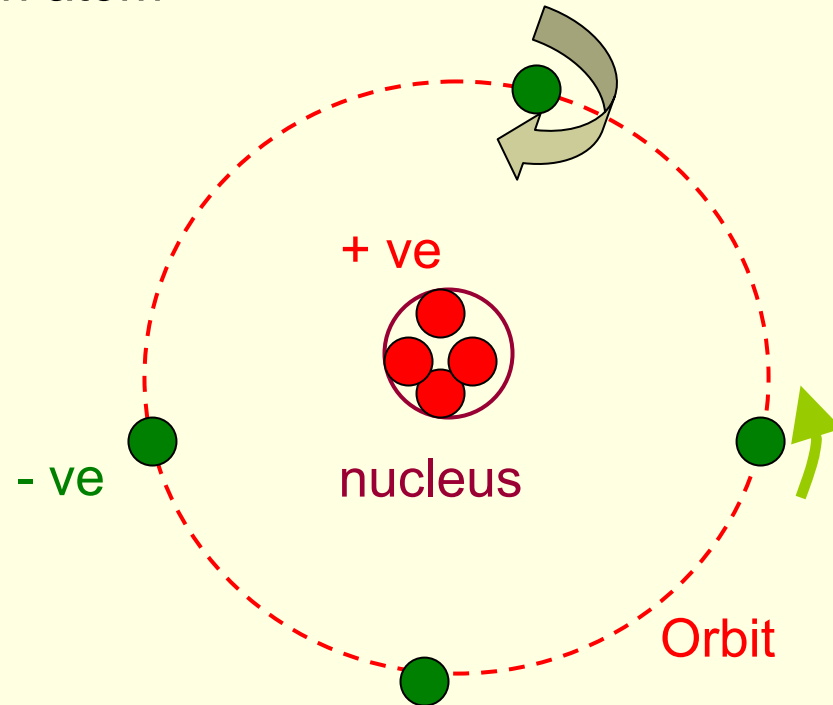
■ APPROACH

- Microscopic point of view
- Macroscopic point of view

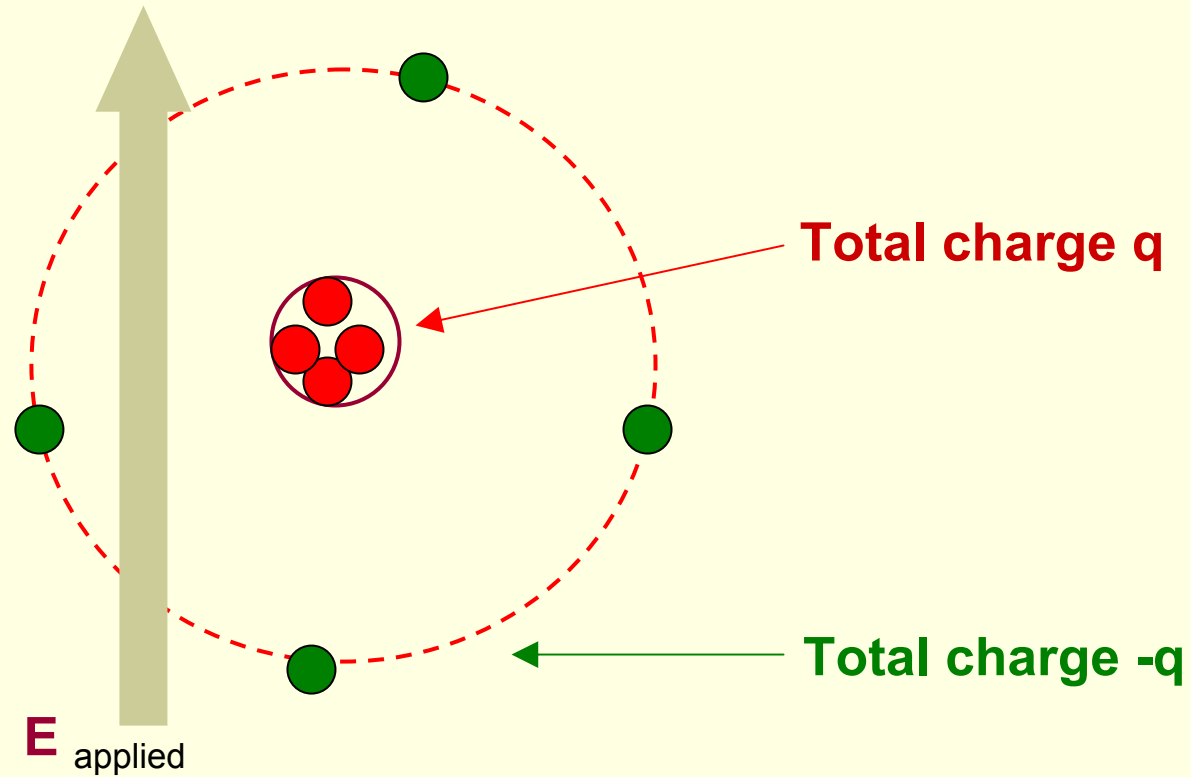
MICROSCOPIC POINT OF VIEW

Classical model of an atom

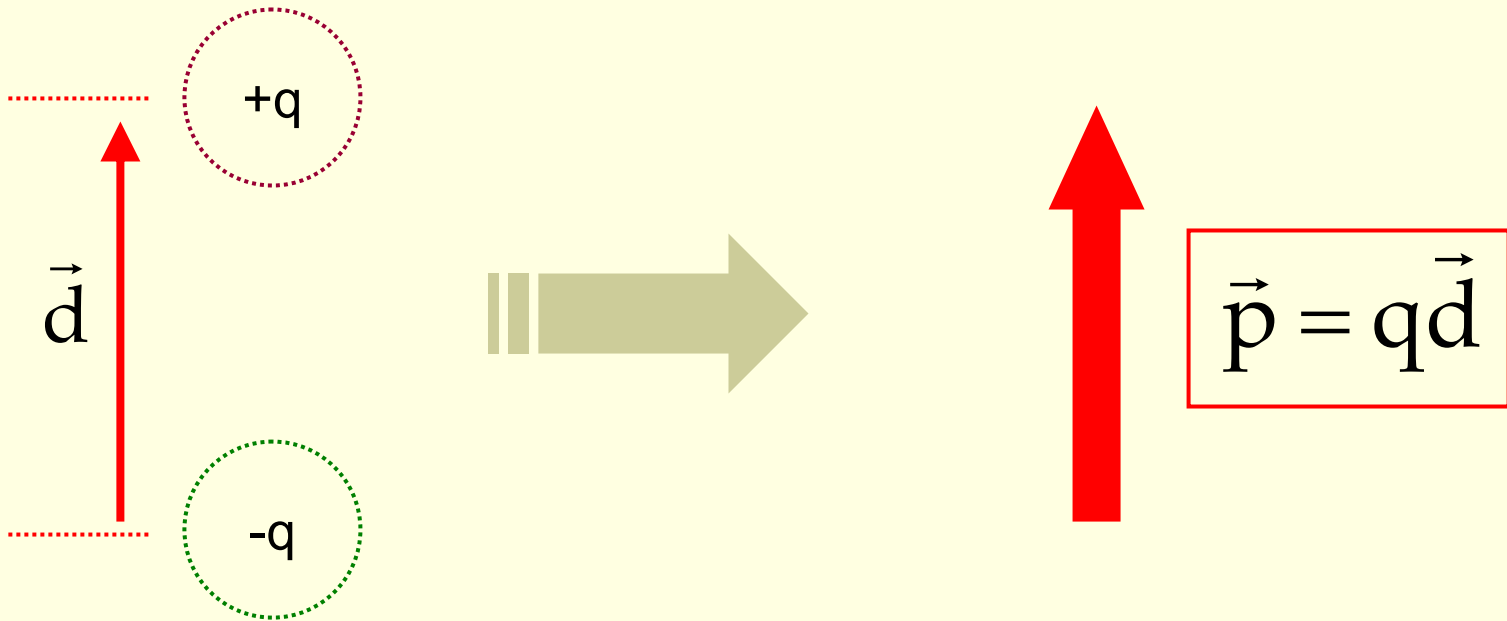
Assume $E_{\text{applied}} = 0$



AN ATOM UNDER STATIC CONDITION



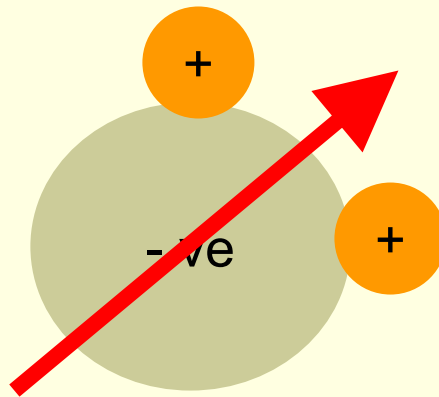
MICROSCOPIC DIPOLE MOMENT



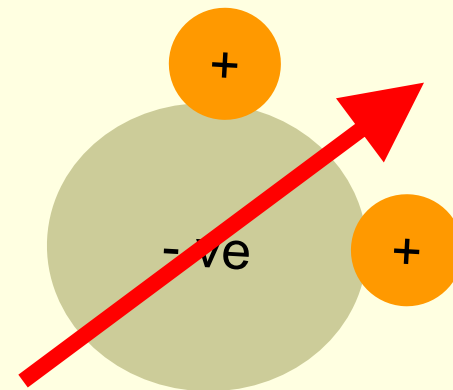
MACROSCOPIC POINT OF VIEW

Assume dielectric material is polar material

H₂O molecule



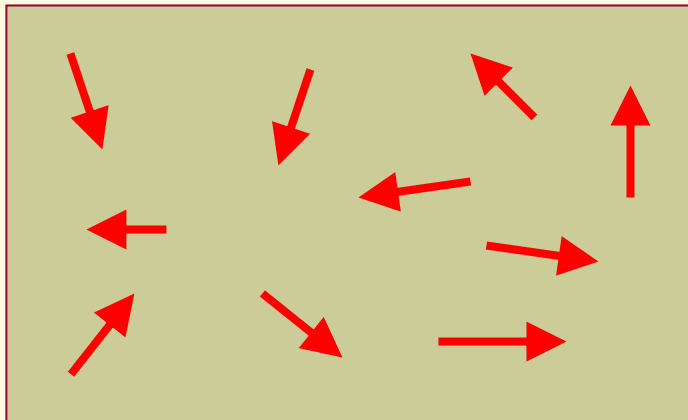
$E_{\text{applied}} = 0$



$E_{\text{applied}} \neq 0$

GROUP OF ATOMS

Assume number of atoms is 10



$$E_{\text{applied}} = 0$$

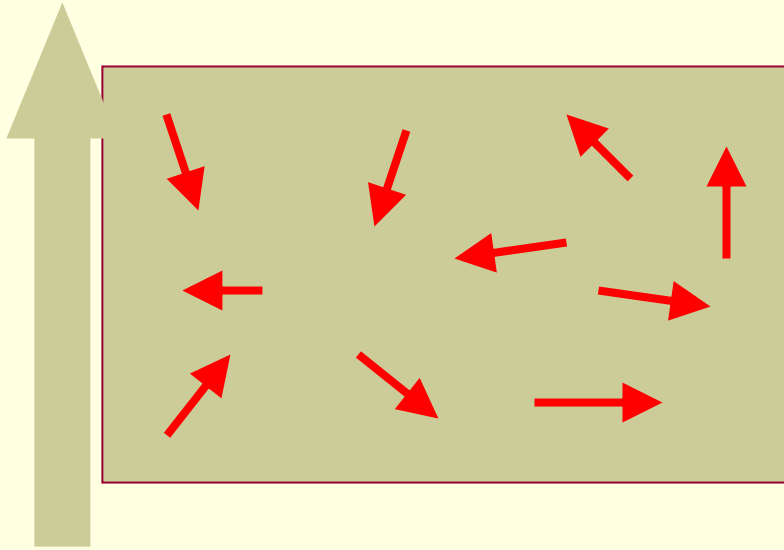
Electric polarization vector

$$\vec{P} = n \vec{p} = 0$$

of atoms

Electric dipole moment

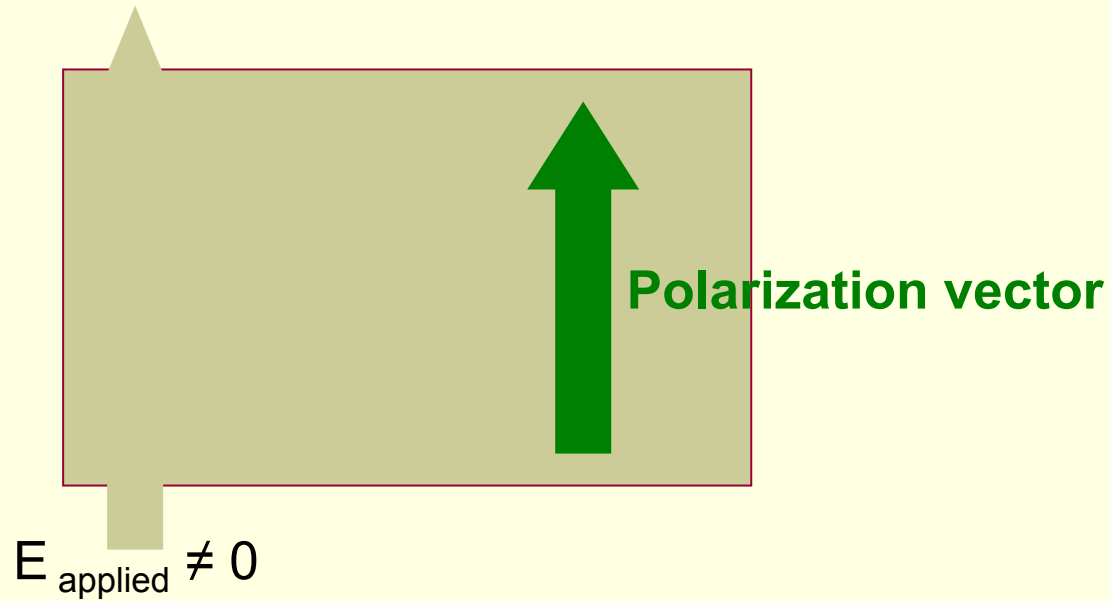
$E_{\text{applied}} \neq 0$



Polarized dielectric material.

$$\vec{P} = n\vec{p} \neq 0$$

REVIEW

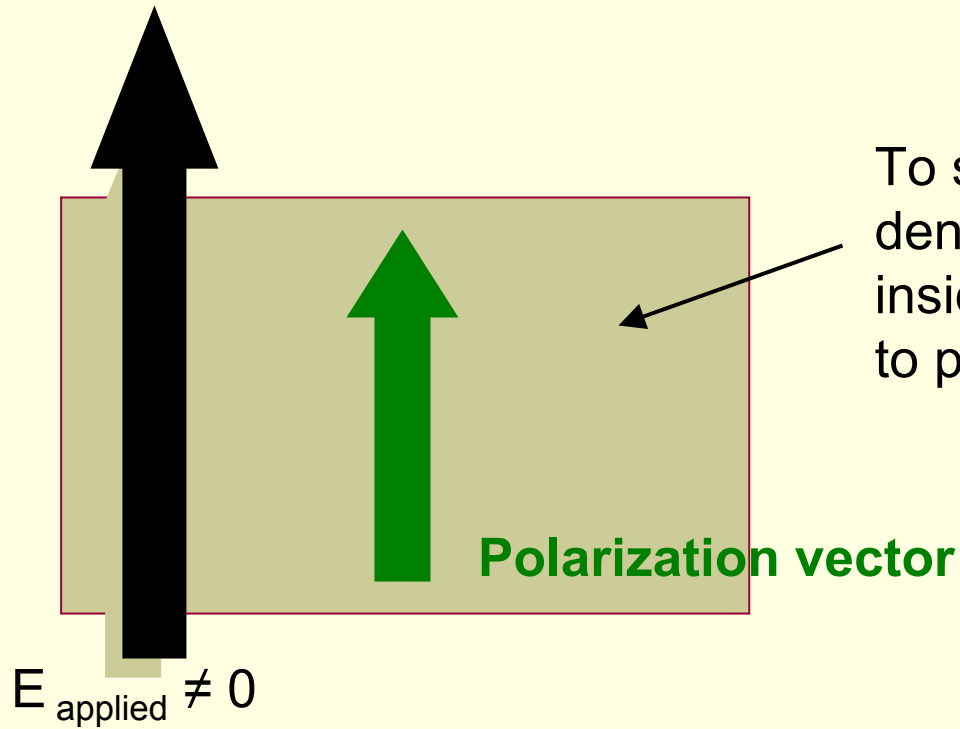


■ BOUND CHARGES

OBJECTIVES

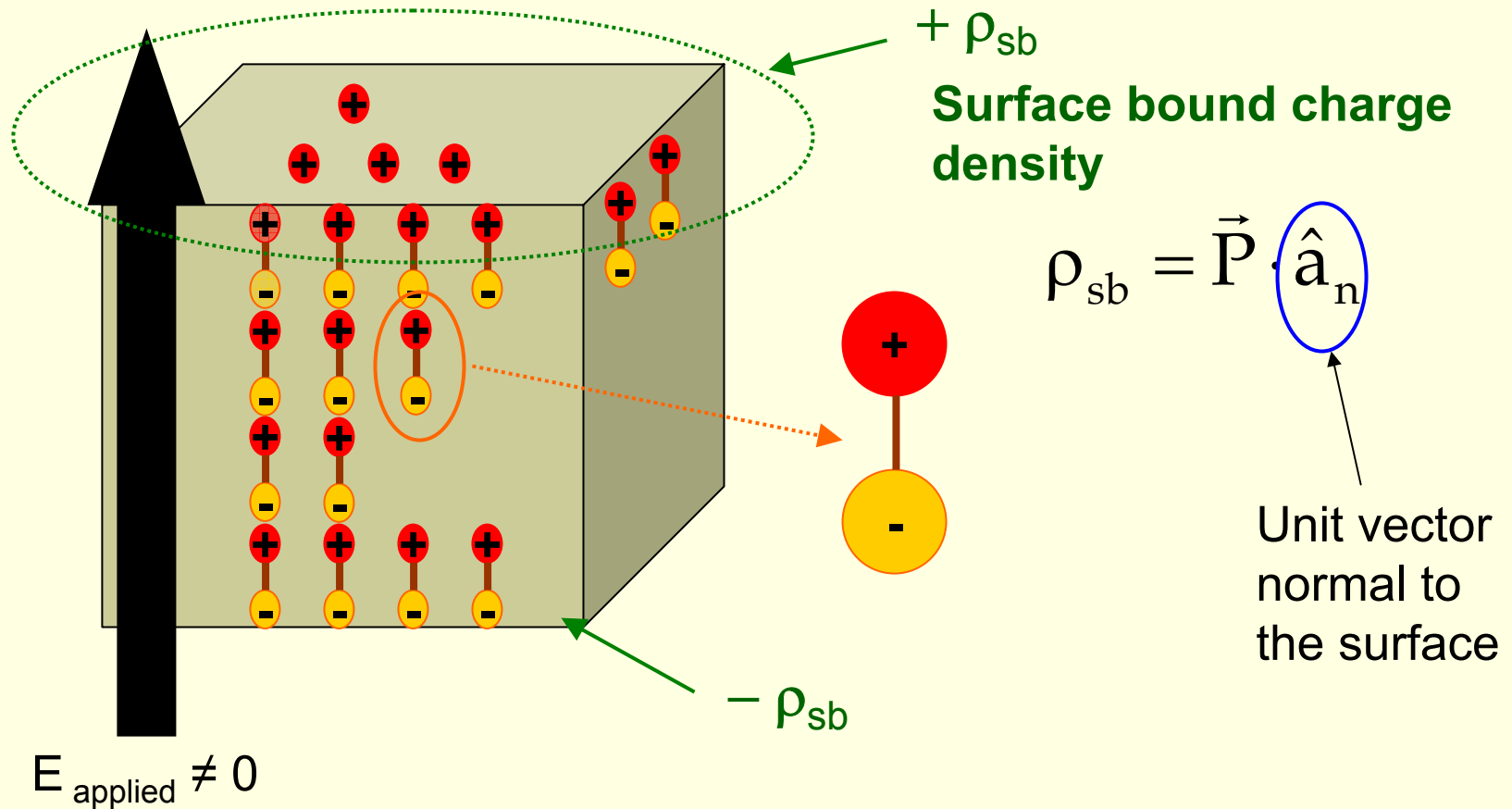
- To show ρ_{sb} and ρ_{vb} can be found within a dielectric due to polarization.
- To derive equations for ρ_{sb} and ρ_{vb} .

REVIEW

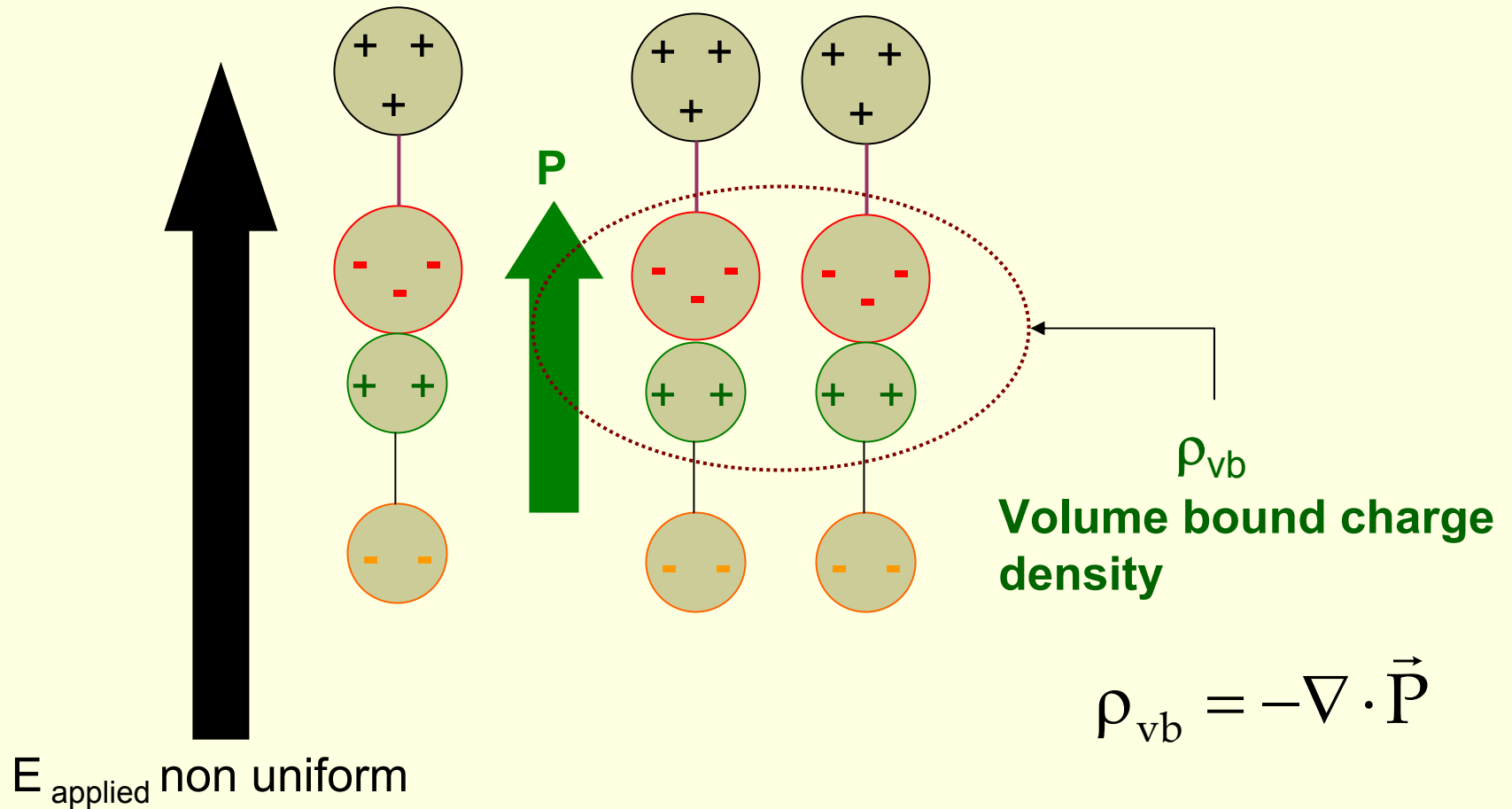


To show bound charges densities can be found inside a dielectric due to polarization.

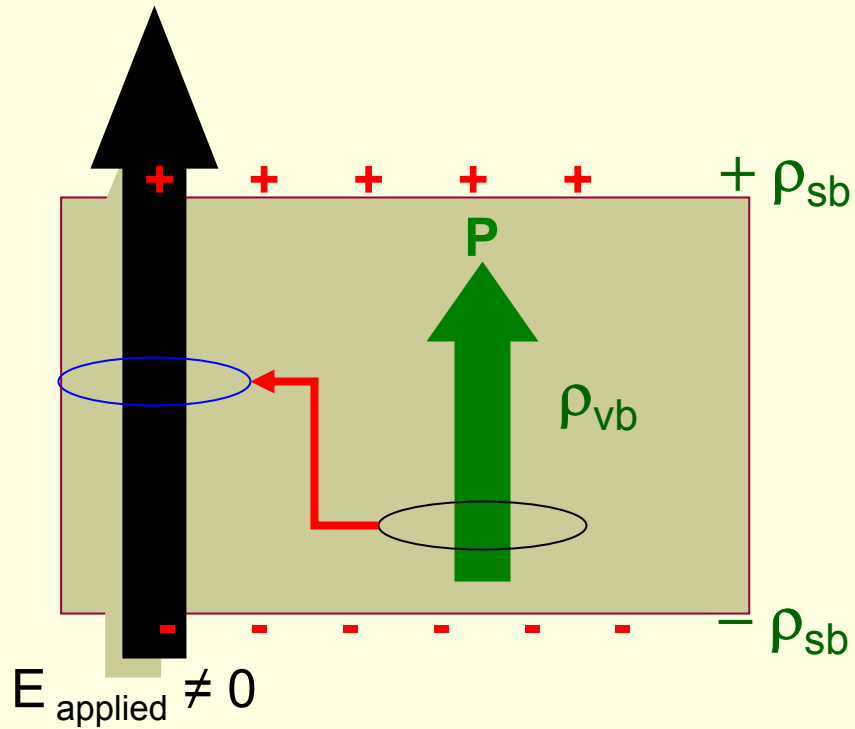
GRAPHICAL ILLUSTRATION (ρ_{sb})



GRAPHICAL ILLUSTRATION (ρ_{vb})



EFFECT OF POLARIZATION ON FIELDS



MATHEMATICAL MODEL

Maxwell's equation (Point form of Gauss's law)

$$\nabla \cdot \vec{D} = \rho_v$$

$$\nabla \cdot \epsilon_0 \vec{E} = \rho_v$$

$$\nabla \cdot \epsilon_0 \vec{E} = \rho_v + \rho_{vb}$$

$$\nabla \cdot (\epsilon_0 \vec{E} + \vec{P}) = \rho_v$$

Free space

General material

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

$$\rho_{vb} = -\nabla \cdot \vec{P}$$

To convert to more familiar form of equation

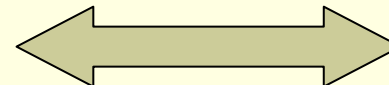
$$\vec{P} = \chi_e \epsilon_0 \vec{E}$$

$$\vec{D} = \epsilon_0 (1 + \chi_e) \vec{E}$$

$$\vec{D} = \epsilon_0 \epsilon_r \vec{E} = \epsilon \vec{E}$$

Electric susceptibility

Relative permittivity



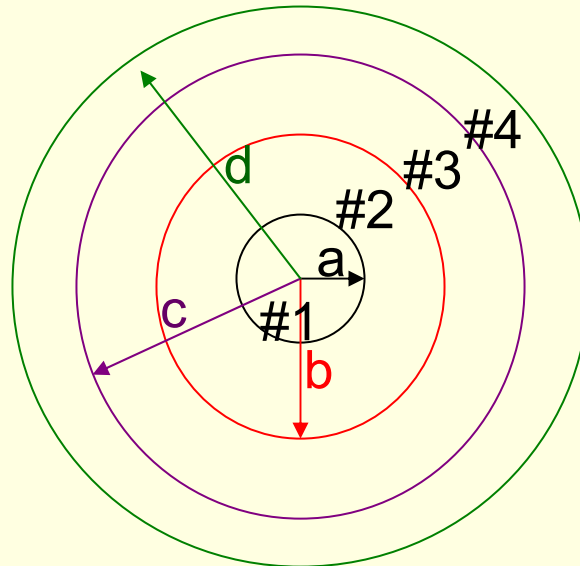
Dielectric constant

DIELECTRIC MATERIALS AT LOW FREQUENCY

Material	ϵ_r	Material	ϵ_r
Air	1.0006	Polyethylene	2.26
Bakelite	4.8	Polystyrene	2.5
Glass	6.0	Quartz	3.8
Lucite	3.2	Soil (dry)	3.0
Nylon	3.6	Teflon	2.1
Plexiglas	3.45	Water	80

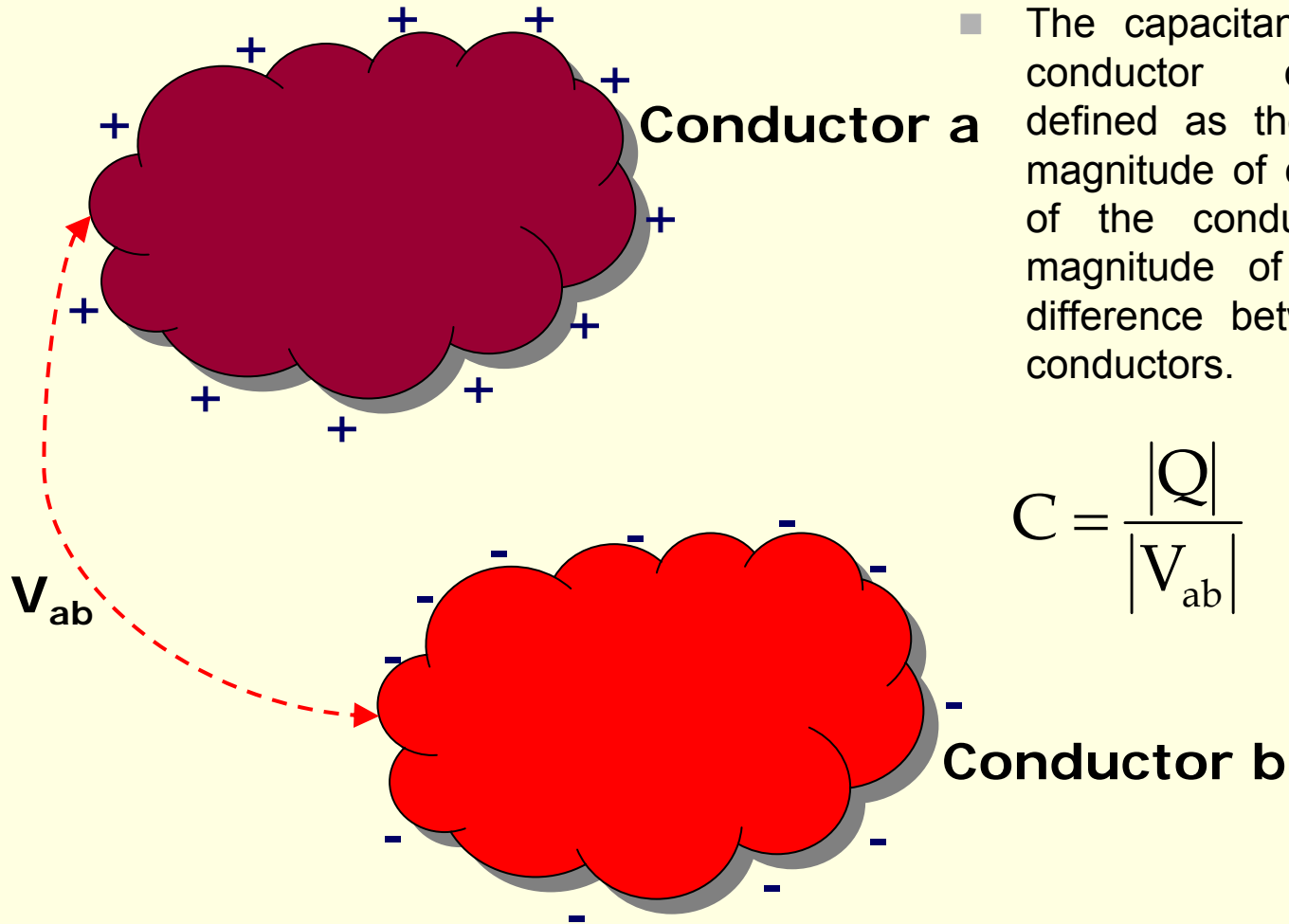
ASSIGNMENT

- An underground spherical configuration of concentric spherical dielectric shells, enclosed by a conductor shell, is shown below. Regions 1 and 3 are free space, region 2 is a dielectric whose relative permittivity is ϵ_r , and region 4 is a conductor. If charge Q is placed at the center, find: (i) \mathbf{D} ; (ii) \mathbf{E} ; (iii) \mathbf{P} ; (iv) ρ_s on the conductor surfaces; (v) ρ_{sb} on the dielectric surfaces; (vi) ρ_{vb} within the dielectric.



■ CAPACITANCE

GRAPHICAL ILLUSTRATION



- The capacitance of a two-conductor capacitor is defined as the ratio of the magnitude of charge on one of the conductors to the magnitude of the potential difference between the two conductors.

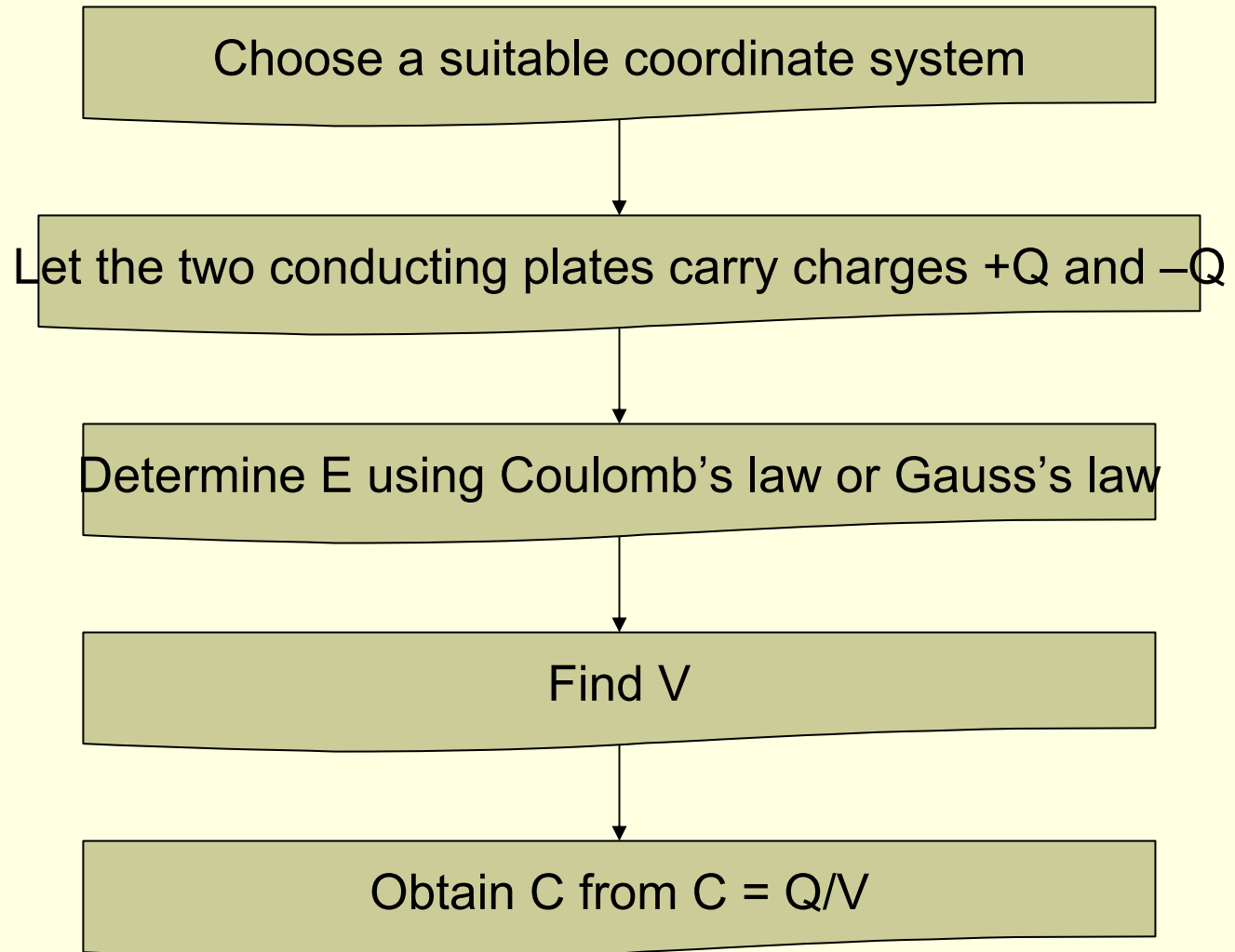
$$C = \frac{|Q|}{|V_{ab}|}$$

MATHEMATICAL MODEL

$$C = \frac{\left| \int_{s_a} \rho_s ds \right|}{\left| - \int_b^a \vec{E} \cdot d\vec{l} \right|}$$

$$C = \frac{\left| \int_{s_a} \epsilon \vec{E} \cdot d\vec{s} \right|}{\left| - \int_b^a \vec{E} \cdot d\vec{l} \right|}$$

APPROACH



SUMMARY

- The capacitance of a two-conductor body and resistance of the medium between them can be computed from knowledge of the electric field in that medium.